

LASER IMAGING SYSTEM

SERVICES

- Engineering Design & Development
- Electronic Testing & Assembly
- CNC Machining and Manufacturing
- System Integration



PRODUCTS

- Electro-Optic Stabilized
 Platforms
- * Radar Sub Systems
- Laser Applications
- * Gimbals
- * Pedestals
- * Motion Control Systems
- Test Benches





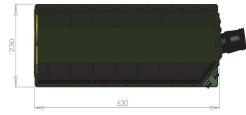


Application Areas

- Sniper Detection
- VIP Security
- Border Protection
- Works in extreme weather conditions
- ◆ Tripod / vehicle mountable

The laser imaging system (LIS) is an Passive surveillance / laser imaging system. It detects any optical system that is in the field of view/ scanning area and give the target Co-ordinates. It is a laser based active imaging system with additional feature of coordinate estimation of the target. The retro-reflected laser illuminated beam from the target optics will be acquired by the front end optics of the receiver and will be read by the image sensor. The Laser retro-reflected spot is detected and the exact location of the reflected spot is estimated through LRF, DMC and GPS readings.







SYSTEM CONTROLS

TECHNOLOGY SOLUTIONS PRIVATE LIMITED



Technical Specifications





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System Specification:

Sensor

Viewing

Laser Receiver FOV

Range of operation 1800 m Source Wavelength 1550 nm Source Power 10W (approx.)

Variable, 1 to 4 deg; slaved with real time FOV of the Imaging Divergence

> Camera through motorized zoom InGaAs FPA (pixels: 640 x 512)

Min; not more than 1 deg

Max; not less than 4 deg (in steps of 0.5 deg)

Monocular + SVGA micro display plus an external 5 to 6 inch

high contrast display with flap as cover

Receiver zoom Optical 4X typical, motorized, plus digital 4X

Interference Filters Narrow band (~40 nm)with peak Tx at 1550 nm and a broad

band (will be optimized for day/night viewing)

Bright Daylight & Moonless / highly overcast: $10^{-3} - 10^{-4}$ lux Operation

Target Range 50m-1800m, with an accuracy of ±5m

Target coordinate

With an angular coordinate accuracy of better than ±8 mrad, computation

GPS accuracy ≤10m

Not worse than 0.1m rad in the entire range of zoom Bore sight accuracy

Size/ weight (approx) 550 X 300 X 200 mm / 12Kg

System Features:

System Configuration Tripod Mounted

Field of regard 360 deg in azimuth, ±10 deg in elevation

Battery Type Li -lon Rechargeable

Duty Cycle Minimum 'On time in active surveillance will be 1 hr, with a

duty cycle of 10min 'ON' and 5min 'OFF', in one time full

battery charge condition

Bright Daylight as well as Moonless night / highly overcast sky: Operation

 $10^{-3} - 10^{-4}$ lux

Day/ Night Mode, Zoom value ,Video recording, Target Video Overlay for

detected ,range/coordinates of target

Inbuilt flash memory 4 GR min

External Interfaces Interface for USB & external monitor, socket for battery charg-

-ing, and battery connection

Soft buttons/switches for System ON/OFF, Transmitter ON/OFF, TLM, Day/Night mode ,Optical/

digital zoom ,Video recording

Charging/Low battery

Indicator One LED will be provided for charging showing green color and low

In video recording mode also

battery showing blinking red color

Zoom in/ Zoom out

Confirmation of target

detection Visual (glowing LED)

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